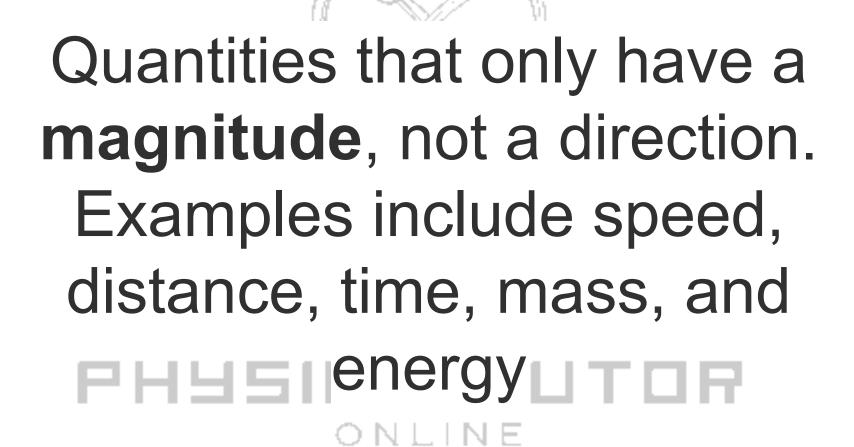
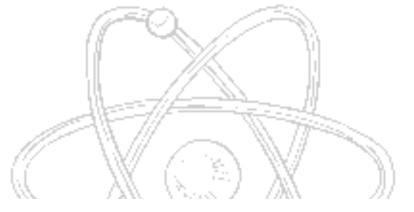


Scalar Quantities







Vector Quantities





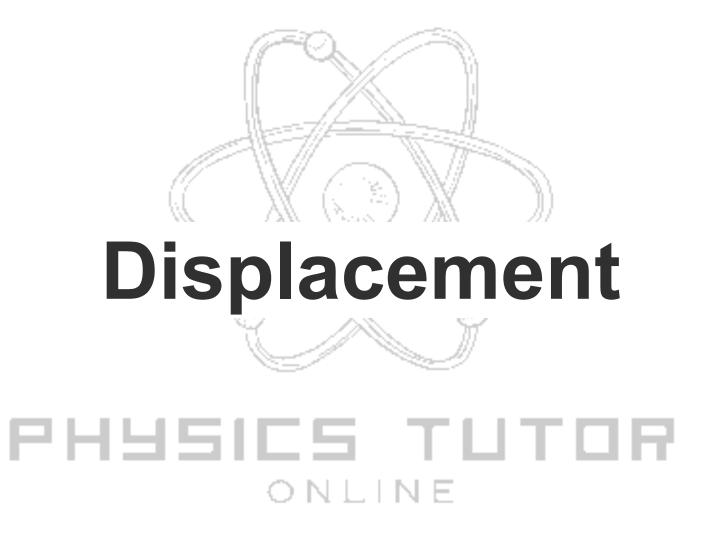
Quantities that have both a magnitude and direction. They are represented by an arrow. Examples include velocity, displacement, acceleration, force, and momentum

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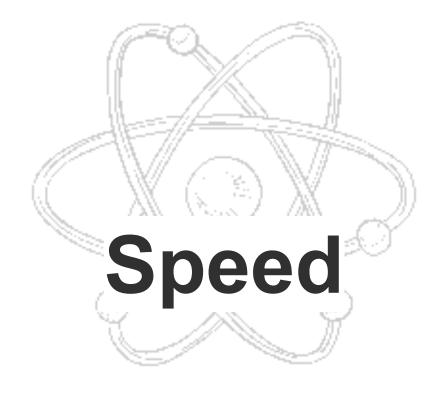




A measure of how far an object moves. It doesn't depend on direction and is therefore a scalar quantity

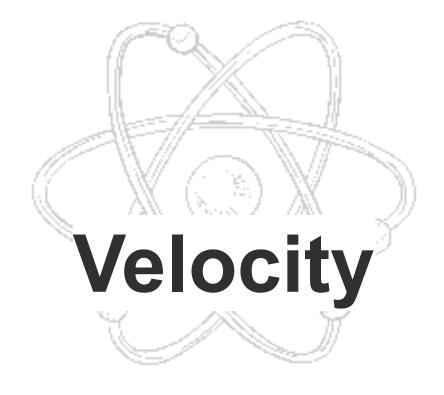


A measure of how far an object moves in a given direction. It is the straight line between the starting and finishing points and is a vector PHⁱ quantity



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A scalar quantity that is a measure of the rate of change of distance. Average speed is calculated by dividing the distance travelled by the time taken



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A vector quantity that is a measure of the rate of change of displacement. It is the speed in a given direction.





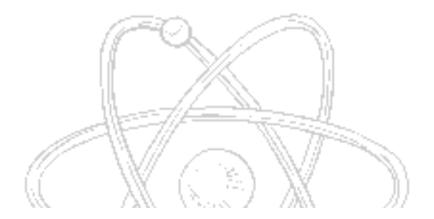
The rate of change of velocity. It can be calculated from the gradient of a velocity-time graph



Acceleration due to Gravity (g)



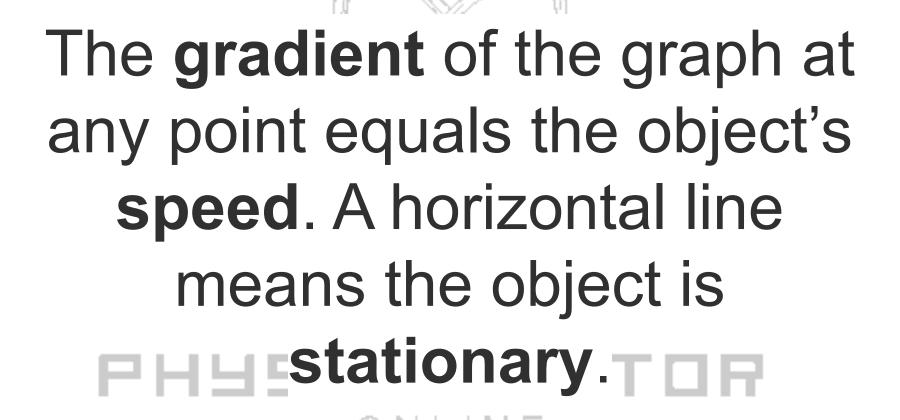
The acceleration experienced by an object travelling in free-fall. Its value at the surface of Earth is 10 m/s² PHHSICS

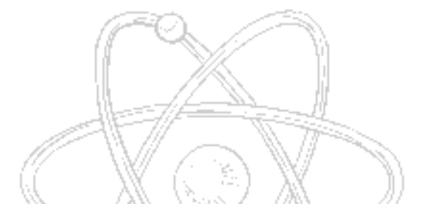


Distance-Time Graph



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Velocity-Time Graph

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The gradient at any point equals the object's acceleration. The area under the graph equals the object's displacement (distance travelled)



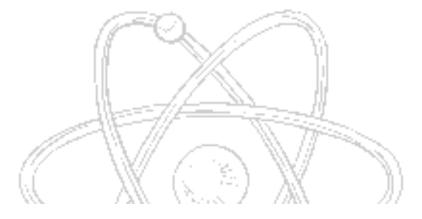
Human Reaction Time



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The time it takes for the brain to react to a stimulus. Typical times are in the range of 0.2-0.9 seconds



Stopping Distance



The sum of the thinking distance and the braking distance



Thinking Distance



The distance a vehicle travels during the driver's reaction time. This is affected by tiredness, drugs, or alcohol.





The distance a vehicle travels under the braking force. Affected by adverse road/weather conditions, and the condition of the vehicle (e.g., bald tyres)



Braking Distance and Speed

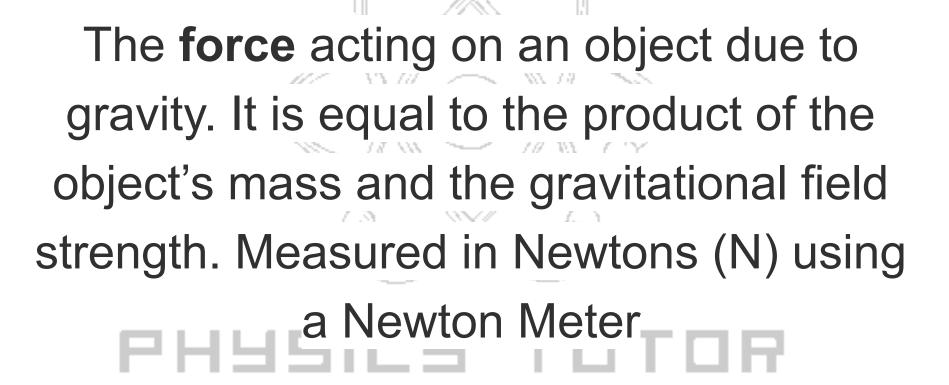




Braking distance is **proportional to the initial velocity squared** $(d \propto u^2)$. The
work done to stop the vehicle equals its
initial Kinetic Energy



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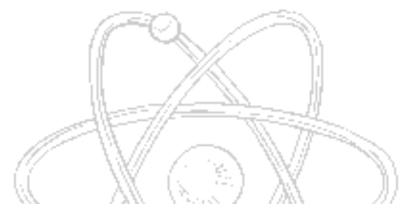




Resultant Force



The single force that can replace all the individual forces acting on an object, and have the same overall effect.

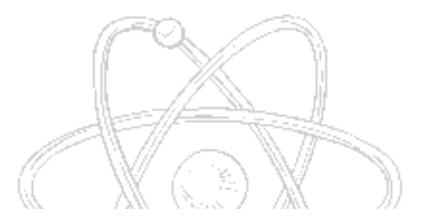


Newton's First Law



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If the resultant force is zero, a stationary object remains stationary, or a moving object continues to move at a constant velocity (same speed and direction).



Newton's Second Law



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An object's acceleration is directly proportional to the resultant force

acting on it, and inversely proportional to the object's mass. Formula: F=ma

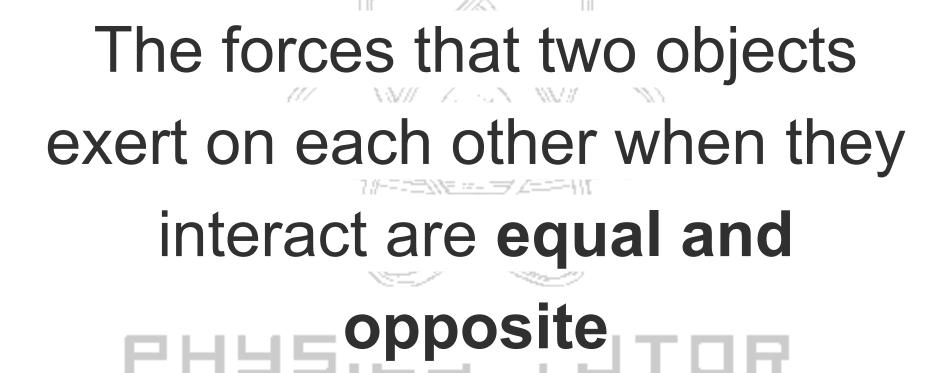
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Newton's Third Law



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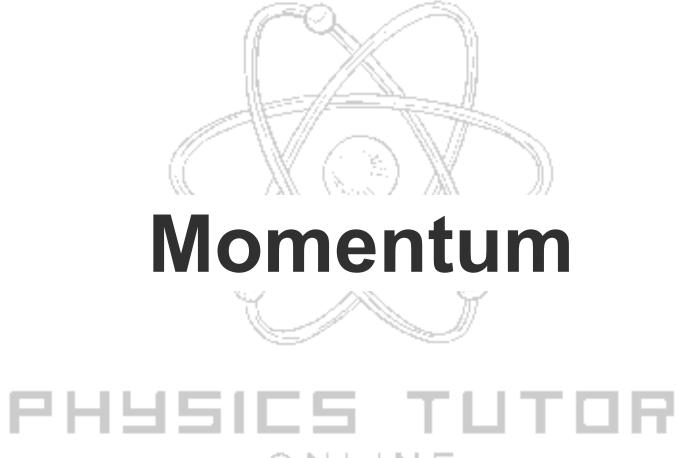




Inertial Mass (Higher

(Tier)

A measure of how hard it is to change an object's velocity. It equals the ratio of force over acceleration.





The product of an object's mass and velocity. Formula:

p=mv. It is a **vector** quantity

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Conservation of

Momentum

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The total momentum of a system **before** an event is always equal to the total momentum **after** the event, assuming no other external forces.



Force (using Momentum

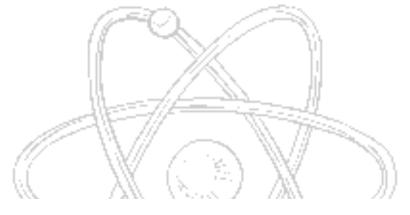
Formula)



Force is equal to the rate of change of momentum.

Formula: F=(mv-mu)/t

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Circular Motion



The motion of an object travelling in a circle. The speed stays constant, but the velocity is always changing because the direction changes continually, meaning the object is always PHH = accelerating | T | P



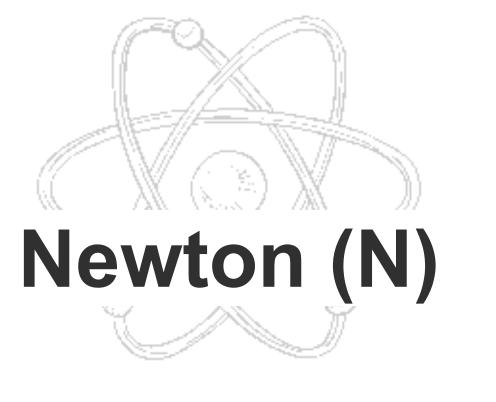
Centripetal Force (Separate

Science)





The resultant force that acts towards
the centre of the circular path of an
object. This force is required because
the object is continually accelerating.









Motion occurring under the force of gravity alone